

On lightweight Hoare logic of probabilistic programs: a bound tighter than the union bound



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Abstract

In the formal verification of probabilistic programming, lightweight Hoare logics are proposed to reason about a bound of the failure probability of non-probabilistic assertions. The existing lightweight Hoare logic, **aHL**, relies on the union bound, a simple tool from probabilistic theory. However, we found that the union bound is loose in general.

In this work, we tighten the bound in **aHL** and prove its soundness and tightness. Downstream tools that rely on **aHL** can directly benefit from our out-of-the-box improvement. Practical applications to demonstrate the superiority of our theoretical improvements are in the plan.

Starting Point: aHL

aHL[1] is based on a standard probabilistic imperative language, whose core grammar is

$$c ::= x \leftarrow e \mid x \leftarrow \$d \mid c; c \mid \text{if } b \text{ then } c \text{ else } c \mid \text{while } b \text{ do } c.$$

An **aHL** judgment is of the form

$$\vdash_{\beta} c : \Phi \Longrightarrow \Psi,$$

which means that from any initial program state satisfying Φ , after executing program c , Ψ holds except with a probability at most β . In other words, β is a bound of the failure probability for c with respect to the specification of precondition Φ and postcondition Ψ .

A key of **aHL** is how to give a bound for the rule of sequential composition. The solution is provided by the *union bound*: for events A and B , $\Pr[A \cup B] \leq \Pr[A] + \Pr[B]$. Internalizing the union bound in the logic, the sequential composition rule [SEQ] of **aHL** is as follows.

$$\frac{\vdash_{\beta_1} c_1 : \Phi \Longrightarrow \Xi \quad \vdash_{\beta_2} c_2 : \Xi \Longrightarrow \Psi}{\vdash_{\beta_1 + \beta_2} c_1; c_2 : \Phi \Longrightarrow \Psi} \text{ [SEQ]}$$

The above rule expresses that if the failure probability for c_1 is no more than β_1 and the failure probability for c_2 is no more than β_2 , the failure probability for $c_1; c_2$ is no more than $\beta_1 + \beta_2$. More detailedly, this rule expresses that if (1) from any state satisfying Φ , after executing program c_1 , Ξ holds except with a probability at most β_1 , and (2) from any state satisfying Ξ , after executing program c_2 , Ψ holds except with a probability at most β_2 , then from any state satisfying Φ , after executing program $c_1; c_2$, Ψ holds except with a probability at most $\beta_1 + \beta_2$.

Figure 1 shows the intuition of this bound. The blue ellipse represents the event that c_1 fails, and the yellow one represents the event that c_2 fails. The blue area is no more than β_1 , and the yellow area is no more than β_2 . Thus, the colored area is no more than $\beta_1 + \beta_2$, which indicates a bound for the event that $c_1; c_2$ fails.

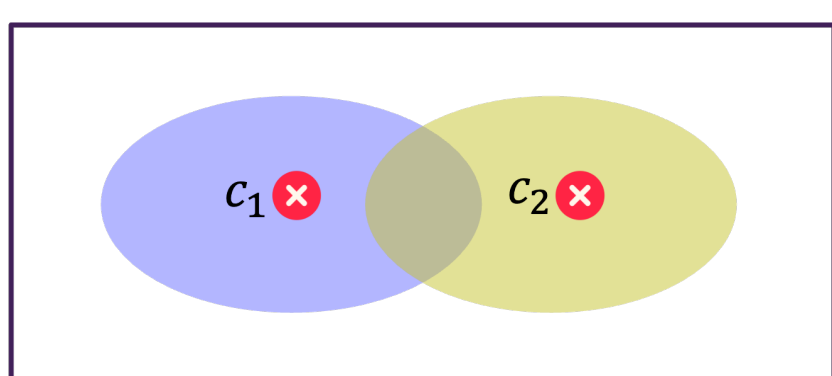


Figure 1: union bound: $\beta_1 + \beta_2$

Critique to aHL

Question We observe that the union bound, $\beta_1 + \beta_2$, may exceed 1, which is a useless case since the probability is always no more than 1 by definition.

However, finding a tight (accurate) failure bound is a fundamental quantitative analysis task for probabilistic programs. Now, a question arises naturally: What bound is tight enough for **aHL**?

Analysis We point out that the union bound ignores the dependence between the two composed programs: only when c_1 does not fail, it is meaningful for us to consider whether c_2 fails, as shown in Figure 2. Roughly speaking, $c_1; c_2$ fails only when c_1 and c_2 do not both succeed, which indicates that $1 - (1 - \beta_1)(1 - \beta_2)$ is a bound.

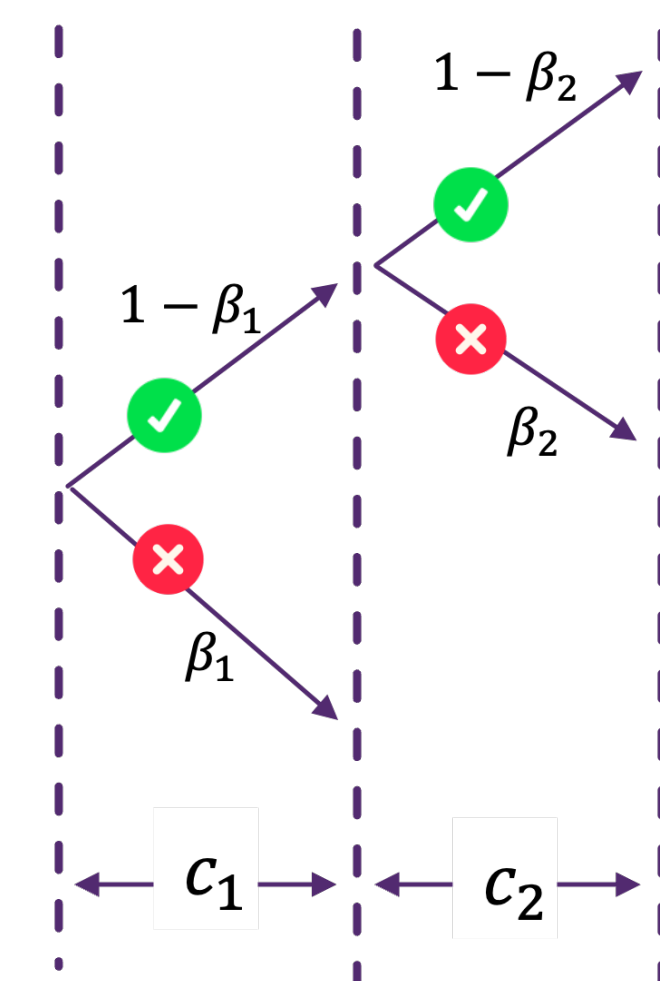


Figure 2: our bound:
 $1 - (1 - \beta_1)(1 - \beta_2) = \beta_1 + \beta_2 - \beta_1\beta_2$

Results

We improve the crucial sequential composition rule [SEQ] as follows.

$$\frac{\vdash_{\beta_1} c_1 : \Phi \Longrightarrow \Xi \quad \vdash_{\beta_2} c_2 : \Xi \Longrightarrow \Psi}{\vdash_{\beta_1 + \beta_2 - \beta_1\beta_2} c_1; c_2 : \Phi \Longrightarrow \Psi} \text{ [SEQ-X]}$$

We prove (with pen and paper) that the rule [SEQ-X] is sound and tight.

Theorem 1 (soundness) For the rule [SEQ-X], if the premise judgments are valid, then the conclusion judgment is valid.

Theorem 2 (tightness) There exist programs and specifications so that applying the rule [SEQ-X] produces the exact failure probability of the conclusion.

In other words, this tightness means that there is a practical application of the rule achieving the bound, which cannot be satisfied in **aHL**.

References

- [1] G. Barthe et al. “A Program Logic for Union Bounds”. In: *43rd International Colloquium on Automata, Languages, and Programming (ICALP 2016)*.